

MRI of the human brain at 130 microtesla

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This contribution is part of the special series of Inaugural Articles by members of the National Academy of Sciences elected in 2012.

Contributed by John Clarke, October 16, 2013 (sent for review August 9, 2013)

We present *in vivo* images of the human brain acquired with an ultralow field MRI (ULFMRI) system operating at a magnetic field $B_0 \sim 130 \mu\text{T}$. The system features prepolarization of the proton spins at $B_p \sim 80 \text{ mT}$ and detection of the NMR signals with a superconducting, second-derivative gradiometer inductively coupled to a superconducting quantum interference device (SQUID). We report measurements of the longitudinal relaxation time T_1 of brain tissue, blood, and scalp fat at B_0 and B_p , and cerebrospinal fluid at B_0 . We use these T_1 values to construct inversion recovery sequences that we combine with Carr–Purcell–Meiboom–Gill echo trains to obtain images in which one species can be nulled and another species emphasized. In particular, we show an image in which only blood is visible. Such techniques greatly enhance the already high intrinsic T_1 contrast obtainable at ULF. We further present 2D images of T_1 and the transverse relaxation time T_2 of the brain and show that, as expected at ULF, they exhibit similar contrast. Applications of brain ULFMRI include integration with systems for magnetoencephalography. More generally, these techniques may be applicable, for example, to the imaging of tumors without the need for a contrast agent and to modalities recently demonstrated with $T_{1\rho}$ contrast imaging (T_1 in the rotating frame) at fields of 1.5 T and above.

High-field MRI (HFMRI), based on the NMR of protons (1, 2), is a powerful clinical tool for imaging the human body (3). The protons, with magnetization M , precess about a static magnetic field B_0 at their Larmor frequency $\omega_0 = \gamma B_0$, where γ is the gyromagnetic ratio, $\gamma/2\pi = 42.58 \text{ MHz/T}$. By Faraday's law, they induce an oscillating voltage $V = \omega_0 M$ in a nearby coil—shunted with a capacitor to form a tuned circuit—that is amplified and recorded. Because M scales with B_0 , V scales as B_0^2 and hence as ω_0^2 . 3D magnetic field gradients specify a unique magnetic field and thus an NMR frequency or phase in each voxel of the subject, so that with appropriate signal decoding one can acquire a 3D image (4).

Clinical MRI systems with $B_0 = 1.5 \text{ T}$ achieve a spatial resolution of typically 1 mm; 3-T systems are becoming increasingly widespread in clinical practice (5), offering a higher signal-to-noise ratio (SNR) and thus higher spatial resolution. Nonetheless, there is ongoing interest in less expensive MRI systems operating at lower fields. Commercially available 0.2- to 0.5-T systems based on permanent magnets offer both lower cost and wider patient aperture than their higher field counterparts, at the expense of spatial resolution. At the still lower field of 0.03 T maintained by a room temperature solenoid, Connolly and co-workers (6, 7) obtained clinically useful SNR and spatial resolution by prepolarizing the protons in a field B_p of 0.3 T. Prepolarization (8) enhances the magnetization of the proton ensemble over that produced by the lower precession field; after the polarizing field is removed, the higher magnetization produces a correspondingly larger signal during its precession in B_0 . Using the same method, Stepisnik et al. (9) obtained MR images in the Earth's magnetic field ($\sim 50 \mu\text{T}$).

In recent years there has been increasing interest (10–36) in NMR and MRI at fields ranging from a few nanotesla to the order of 100 μT . The enormous reduction in the detected signal amplitude compared with the high field value is overcome partly

by using prepolarization and partly by detecting the signal with an untuned superconducting input circuit inductively coupled to a superconducting quantum interference device (SQUID) (37). In contrast to a conventional receiver coil, the response of the SQUID-based detector is independent of frequency, so that its sensitivity to an oscillating magnetic field does not fall off as the frequency is lowered. Furthermore, the application of a prepolarizing field $B_p \gg B_0$ produces a proton magnetization M_p that is independent of B_0 . The combination of the frequency-independent SQUID response and prepolarization yields a signal amplitude output from the SQUID that is independent of B_0 and scales as B_p .

Several authors have used ultralow-field (ULF) MRI systems to obtain *in vivo* images of the arm (17) and brain (26, 29, 33, 35). Zotev et al. (29) used a 7-SQUID system to obtain T_2 -weighted images of the brain using multiple echoes produced by periodically reversing the direction of B_0 ; they also obtained values of T_1 . Here, T_1 and T_2 are the longitudinal and transverse relaxation times, respectively. More recently, Vesonen et al. (35) used a 48-SQUID system to obtain T_2 -weighted images using a single-echo sequence. Each of these groups has demonstrated the combination of ULFMRI and magnetoencephalography (MEG) (38, 39), using the same array of SQUIDs in a single system (15, 26, 33, 35).

ULFMRI systems make use of the myriad pulse sequences developed for HFMRI and obtain images using magnetic field gradients in much the same way. A particular advantage of ULFMRI, however, is that the T_1 difference between tissue types can be much greater than at high field (18, 34, 40, 41). In this paper, our emphasis is on using this high intrinsic T_1 contrast, combined with Carr–Purcell–Meiboom–Gill (CPMG) multiple

Significance

We describe MRI in a magnetic field of 130 μT with signals detected from prepolarized protons with a superconducting quantum interference device (SQUID). We report measurements of the longitudinal relaxation time T_1 of brain tissue, blood, scalp fat, and cerebrospinal fluid. Using a combination of inversion recovery and multiple echoes, we form images in which one species can be nulled and another species emphasized. In particular, we show an image in which only blood is visible. Such techniques greatly enhance the already high intrinsic T_1 -contrast obtainable at ultralow frequencies. We further present 2D brain images of T_1 and the transverse relaxation time T_2 showing that, as expected, they exhibit similar contrast.

Author contributions: B.I., K.B., P.S., and J.C. designed research; B.I., K.B., P.S., A.F.P., and M.A.N. performed research; B.I., K.B., and J.C. analyzed data; and B.I., K.B., and J.C. wrote the paper.

The authors declare no conflict of interest.

See QnAs on page 19178.

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This article contains supporting information online at www.pnas.org/lookup/suppl/doi:10.1073/pnas.1319334110/-DCSupplemental.

spin echoes (42–44) and inversion recovery (IR) (41), to image selectively tissues in which there are four widely different values of T_1 : the scalp fat surrounding the skull, brain tissue, cerebrospinal fluid (CSF), and blood. We present T_1 values for these components and demonstrate a variation in relaxation time greater than an order of magnitude.

We begin with a brief description of our ULFMRI system and describe the relevant pulse sequences. We report in vivo values of T_1 and use them to construct IR sequences that, coupled with multiple echoes, produce 2D images consisting solely of brain tissue, blood, or CSF. We acquire T_1 and T_2 maps of the brain, demonstrating that T_1 and T_2 weighting produces similar contrast, and show that the latter can be obtained in a much shorter time. We conclude with a discussion and outlook.

System Description and Imaging Pulse Sequences

System Configuration. The heart of our detection system is the dc SQUID, a superconducting device that combines the phenomena of Josephson tunneling and flux quantization (37). The SQUID consists of two Josephson junctions connected in parallel on a superconducting loop (Fig. 1A). With the SQUID biased in the voltage state, the application of a steadily changing magnetic flux through the loop causes the voltage to oscillate with a period of one flux quantum, $\Phi_0 = h/2e \approx 2.07 \times 10^{-15} \text{ Tm}^2$. Here, h is Planck's constant and e is the electron charge. The SQUID is operated near the flux bias $(2n+1)\Phi_0/4$, at which a small change in magnetic flux $\delta\Phi$ produces a voltage change δV that is amplified by conventional semiconductor electronics. The amplified signal is fed via a resistor into a coil inductively coupled to the SQUID to produce negative feedback. This flux-locked loop maintains the flux in the SQUID at a constant value and provides a voltage output that is linear in the applied flux even though the applied flux corresponds to many flux quanta. In a typical SQUID operated at 4.2 K, the flux noise is typically $1\text{--}5 \mu\Phi_0 \text{ Hz}^{-1/2}$. SQUIDs are fabricated from thin films, commonly in the square washer configuration shown in Fig. 1A. For most applications, a multiturn, thin-film superconducting coil is deposited on the SQUID with an intervening insulating layer. Fig. 1A shows this input coil connected to a second-derivative gradiometer, wound from Nb wire; the baseline and loop diameter are both 76 mm. A magnetic field applied to the lowest loop of this closed superconducting circuit induces a supercurrent and hence a flux in the SQUID loop. This flux transformer increases the sensitivity to nearby magnetic sources while providing a high level of rejection to distant magnetic noise sources. In our system, the magnetic field noise of the detector, referred to the lowest loop, is typically $0.7 \text{ fT Hz}^{-1/2}$. The gradiometer and SQUID are

immersed in liquid helium contained in a low-noise fiberglass dewar with negligible magnetic noise (45), fabricated in-house.

Fig. 1B shows a schematic of our ULFMRI system (12). All coils are wound from copper wire. Two pairs of coils (B_{Cx} and B_{Cy}) wound on the faces of the 1.8-m cube, constructed from $37 \times 87\text{-mm}$ lumber, cancel the Earth's field over the imaging region in the x and y directions to within $\pm 5 \mu\text{T}$. A Helmholtz pair wound on 19-mm plywood forms reinforces the z component of the Earth's field to produce the imaging field B_0 —ranging from 125 to $135 \mu\text{T}$ —along the z axis. We choose the actual value of B_0 to minimize the noise. A Maxwell pair produces the diagonal gradient field $G_z \equiv \partial B_z / \partial z$, two sets of planar gradient coils produce off-diagonal fields $G_x \equiv \partial B_z / \partial x$ and $G_y \equiv \partial B_z / \partial y$ (G_y is not used in this work), and an excitation coil provides oscillating pulses B_1 to manipulate the polarization. A 1.5-mm-thick aluminum shield surrounding the entire system reduces environmental magnetic field noise. A Tecmag Orion console generates the imaging pulse sequences and acquires the signals from the SQUID.

The water-cooled prepolarization coil, wound from $4 \times 4\text{-mm}^2$ hollow copper tubing, consists of 240 turns with an inner radius of 0.16 m. This coil generates a field B_p of up to 150 mT at its center along the x axis, falling to about 80 mT directly under the dewar, 0.15 m above the midplane of the coil. To avoid overheating of the polarizing coil, the maximum pulse duration, t_{Bp} is limited to 720 ms. The axis of the B_p coil is orthogonal to the axes of the coils producing B_0 , B_1 and the gradient fields to minimize its mutual inductance to these coils. Because B_p is perpendicular to B_0 , at the end of the polarization pulse, an adiabatic sweep field $B_{asf} = 650 \mu\text{T}$ is applied along the direction of B_0 for the 10 ms during which B_p is switched off to align the spins adiabatically with B_0 . A further 18-ms delay is required to allow eddy currents in the shield to decay and for relays to disconnect the polarizing coil. Immediately afterward, we apply conventional MRI pulse sequences.

Prepolarization, Spin Echoes, Spatial Encoding, and Inversion Recovery.

We acquire our data using a prepolarized, spin-echo imaging sequence with frequency encoding (FE) for 1D imaging and adding spin warp phase encoding (PE) (46) for 2D imaging. As appropriate, we implement CPMG multiple spin echoes and IR. The imaging sequence begins with the prepolarization pulse (Fig. 2A, *i*) B_p , of duration t_{Bp} , during which the proton longitudinal magnetization M_{\parallel} (Fig. 2A, *ii*) increases as $[1 - \exp(-t_{Bp}/T_1^{Bp})]$ toward its equilibrium value M_p^{max} . Here, T_1^{Bp} is the longitudinal relaxation time in the field B_p . After B_p is turned off in the presence of the adiabatic sweep field (Fig. 2A, *iii*), M_{\parallel} decays exponentially (Fig. 2A, *ii*) with time constant T_1^{B0} , the longitudinal relaxation

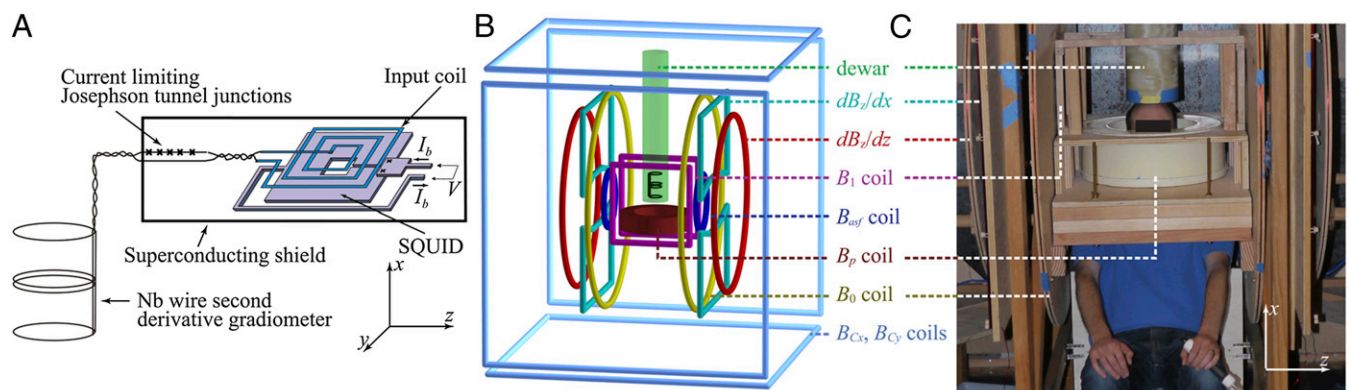


Fig. 1. System configuration. (A) Schematic of the SQUID and gradiometer. The SQUID is 1 mm across, and the resistance of the current limiter in its voltage state is $\sim 700 \Omega$. (B) Principal components of the ULFMRI system. (C) Photograph of the ULFMRI system with a subject positioned for head imaging.

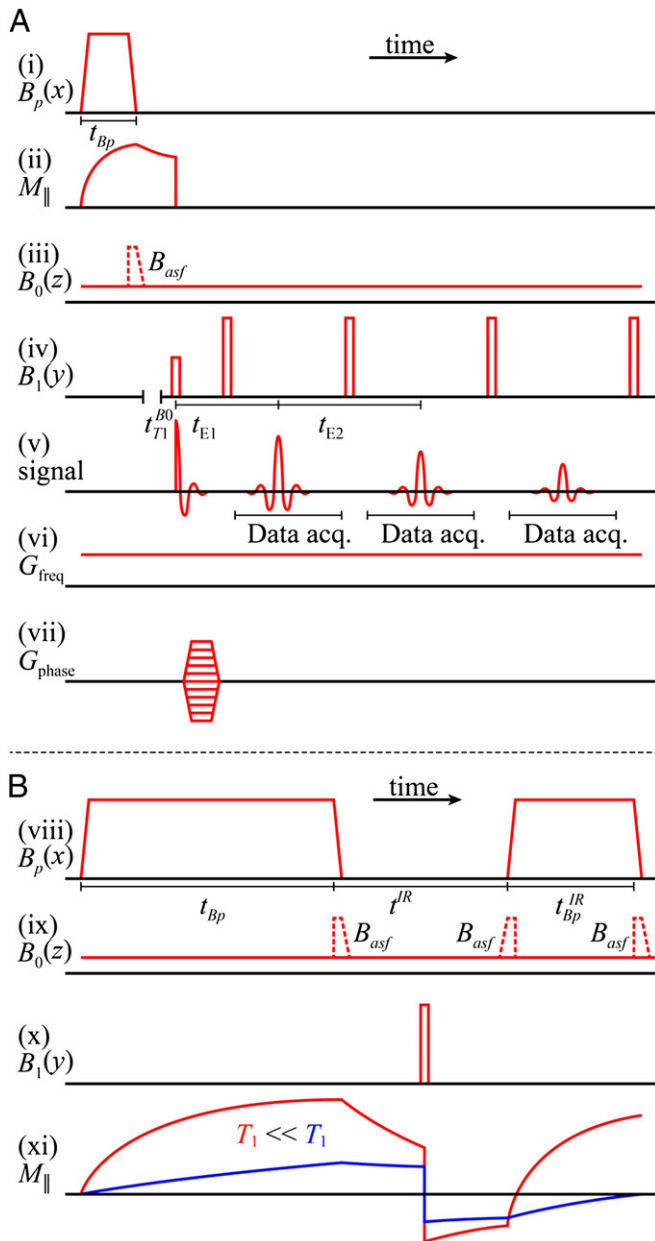


Fig. 2. Pulse sequences. (A) Prepolarized CPMG 2D imaging sequence. (i) Prepolarization pulse. (ii) Resulting longitudinal magnetization. (iii) B_0 field that remains on throughout data acquisition; dashed pulse is the adiabatic sweep field B_{asf} . (iv) CPMG pulse sequence. (v) Spin echoes. (vi) Frequency encoding gradient. (vii) Phase encoding gradients. (B) IR contrast presequence applied before the imaging sequence (A) to null out selected species. (viii) Prepolarization pulse followed by IR polarizing pulse. (ix) B_0 field and adiabatic sweep fields. (x) 180° inverting pulse. (xi) Longitudinal magnetization.

time in B_0 . There is an optimal value $t_{Bp} \approx 1.25 T_1^{Bp}$, which is a compromise between polarizing for a longer time to increase $M_{||}$ and polarizing for a shorter time to increase the repetition rate of the sequence (21).

We tip the magnetization into the x - y plane (Fig. 2A, iv) with a 90° pulse oscillating at the Larmor frequency. Subsequently, a refocusing 180° pulse applied at a time $t_{E1}/2$ after the initial excitation pulse produces the first spin echo (Fig. 2A, v) at a time $t_{E1}/2$ later. To improve the SNR, we choose t_{E1} to be short. The signal is digitized at a sampling rate of 160 kHz, producing

16,384 data points in each acquisition period $t_{ACQ} = 102.4$ ms. As appropriate, further refocusing pulses and spin echoes occur at multiples of t_{E2} to produce a CPMG sequence (Fig. 2A, iv). The echo peak amplitudes decay exponentially with time constant T_2 .

For 1D imaging, frequency-encoded data are acquired in the presence of a gradient $G_{freq} = 90 \mu\text{T/m}$ that remains on throughout the pulse sequence (Fig. 2A, vi). We produce 1D images using Fourier transformation with respect to $k_{freq}^{max} = 2\pi\gamma G_{freq}\tau$, where $\tau = t_{ACQ}/2$. The digital resolution in the frequency-encoded dimension, established by the Nyquist sampling theorem, is $\Delta l_{freq} = \pi/k_{freq}^{max}$, corresponding to a nominal spatial resolution of 2.5 mm. To produce 2D images a phase encoding gradient, G_{phase} , is applied in the first $t_{E1}/2$ period for $t_{phase} = 30$ ms so that $k_{phase}^{max} = 2\pi\gamma G_{phase}^{max} t_{phase}$ (Fig. 2A, vii). We increment G_{phase} in steps of $4.66 \mu\text{T/m}$ to a maximum value of 107 or 140 $\mu\text{T/m}$. The digital resolution in the phase-encoded dimension, also defined by the Nyquist theorem, is $\Delta l_{phase} = \pi/k_{phase}^{max}$, leading to a spatial resolution of 1.9 or 2.5 mm for $G_{phase}^{max} = 140$ or 107 $\mu\text{T/m}$, respectively. We retain only magnitude information in both 1D and 2D image data.

For some applications, we modify the imaging sequence to include a presequence that is equivalent to IR in HFMRI (Fig. 2B). The initial polarizing pulse (Fig. 2B, viii) B_p of duration t_{Bp} , turned off with an accompanying adiabatic sweep field (Fig. 2B, ix), is followed by an evolution delay t^{IR} , during which a B_1 180° pulse inverts the magnetization (Fig. 2B, x and xi). The 180° pulse may be placed at any point during t^{IR} . The evolution delay is followed by an IR polarizing pulse (Fig. 2A, viii) with amplitude B_p and duration t_{Bp}^{IR} . The longitudinal magnetization at the end of the IR pulse is given by

$$M_{||} = M_0 \left\{ 1 + \left[1 - \exp\left(-t_{Bp}/T_1^{Bp}\right) \right] \exp\left(-t^{IR}/T_1^{B0}\right) \right\} \times \left[1 - \exp\left(-t_{Bp}^{IR}/T_1^{Bp}\right) \right] - M_0 \left[1 - \exp\left(-t_{Bp}/T_1^{Bp}\right) \right] \times \exp\left(-t^{IR}/T_1^{B0}\right). \quad [1]$$

The imaging pulse sequence follows. Given measured values of T_1 , we use Eq. 1 to find the values of t_{Bp} , t^{IR} , and t_{Bp}^{IR} required to establish a signal null for any species, as in high-field IR imaging.

Head Imaging. We obtained detailed MRI data from two healthy men, subjects A (age 32 y) and B (age 23 y). Data from subject A are presented below. The protocol was approved by the Human Subjects Committees of the Lawrence Berkeley National Laboratory and the University of California, Berkeley, and informed consent was obtained from both subjects. The subject was seated in a chair with his head protruding through the polarizing coil (Fig. 1C) to touch the bottom of the dewar. A chinstrap attached to the dewar, and an arrangement of memory-foam cushions between the head and polarizing coil restricted motion of the head during imaging.

For 1D measurements of T_1 , the subject tilted his head approximately 20° to his left, placing the central sulcus of the brain's right hemisphere under the dewar. The tilted position prevented a large blood vessel, the superior sagittal sinus (SSS), from being located directly beneath the receiver coil, enabling us to measure brain tissue T_1 with better specificity. We used 1D images to obtain T_1 values for the major brain components: gray matter (GM), white matter (WM), and CSF. However, the presence of signal from scalp fat—which is comprised primarily of long chain lipid molecules—necessitated one further pair of T_1 measurements. The skull is comprised of osseous tissue with low water content (and short T_1 and T_2) and, as in HFMRI, does not contribute significant MR signals. The frequency-encoding gradient was oriented orthogonally to the surface of the head, in the head-to-foot direction (x axis). Our 1D images are thus projections along x of all signals in the y - z plane that reside in the

Table 1. Parameters for five pulse sequences

Row	Sequence	t_{Bp} (ms)	t^{IR} (ms)	t_{Bp}^{IR} (ms)	t_{T1}^{B0} (ms)	t_{E1} (ms)	t_{E2} (ms)	No. echoes	No. averages	No. PE steps	PE resolution (mm)	FE resolution (mm)	Acquisition time
1	SE(T_1^{B0})	420	—	—	18–7,018	74	—	1	4	—	—	2.5	5 min, 32 s
2	SE(T_1^{Bp})	70–720	—	—	18	74	—	1	4	—	—	2.5	1 min, 34 s
3	CPMG/IR CPMG	500/500	—/77	—/90	18/18	74/74	169/169	8/8	6/6	54/54	1.9	2.5	25 min, 52 s
4	SE(T_1^{B0})	500	—	—	18–4,018	74	—	1	1	47	2.5	2.5	19 min, 20 s
5	CPMG(T_2^{B0})	500	—	—	18	74	169	8	2	61	1.9	2.5	4 min, 26 s

SE(T_1^{B0}), 1D spin echo sequence to acquire T_1 in B_0 ; SE(T_1^{Bp}), 1D spin echo sequence to acquire T_1 in B_p ; CPMG/IR CPMG, interleaved CPMG and IR-CPMG sequences for 2D brain imaging; SE(T_1^{B0}), spin echo sequence to obtain 2D T_1 map; CPMG(T_2^{B0}), spin echo sequence to obtain 2D T_2 map.

gradiometer field of view. This arrangement restricts scalp fat signals to that part of the head placed directly under the dewar, enabling us to separate fat signals from the brain signals beneath.

For 2D images, the subject was positioned upright with the midline of his brain oriented in the x - y plane (Fig. 1C). For 2D images, we used frequency encoding along the z axis and phase encoding along the x axis; the third dimension (y axis) was a projection onto the x - z plane of the signals parallel to y .

Relaxation Time Measurements with 1D Imaging. Using frequency encoding, we obtained 1D images of the head on which we defined regions of interest based on features that we identified from a general knowledge of the structure of the head and brain. To measure T_1^{B0} , we varied the delay time, t_{T1}^{B0} , between turning off B_p and applying the 90° pulse (Fig. 2A, iv). Each T_1^{B0} -weighted signal was acquired as a separate spin echo at $t_{E1} = 74$ ms. We used 39 values of t_{T1}^{B0} distributed approximately logarithmically from 18 to 7,018 ms. We performed exponential fits of signal magnitude vs. t_{T1}^{B0} to compute T_1^{B0} for each region of interest. To obtain T_1^{Bp} , we varied the duration, t_{Bp} , of the 80-mT polarizing pulse (Fig. 2A, i). Each T_1^{Bp} -weighted signal was again acquired as a separate spin echo at $t_{E1} = 74$ ms. We incremented the prepolarizing delay, t_{Bp} , from 70 to 720 ms in 13 steps of 50 ms. We computed T_1^{Bp} for each region of interest as for the measurements of T_1^{B0} . Rows 1 and 2 in Table 1 list other acquisition parameters.

2D Brain Imaging. Coronal head images were obtained using interleaved CPMG and IR-CPMG sequences (Table 1, row 3). We used an interleaved acquisition, with one phase encoding step performed for each pulse sequence in turn, to minimize image subtraction errors that might arise from head motion.

The values of T_1 (determined in the 1D imaging experiments) are summarized in Table 2 and, subject to the maximum polarization time, were used to determine the pulse and delay times in the IR sequence. The sequence timing was calculated to null out the signal from the brain tissue [setting Eq. 1 equal to zero using the apparent T_1 of brain tissue, T_1^{*B0} (brain), and assuming that each voxel contains a single tissue component] while maximizing Eq. 1 for CSF. We found $t_{Bp} = 500$ ms, $t^{IR} = 77$ ms, and $t_{Bp}^{IR} = 108$ ms. Although these estimates gave remarkably good starting points to null the brain, we empirically decreased t_{Bp}^{IR} from 108 to 90 ms to obtain the best possible null. Once we had optimized the value of t_{Bp}^{IR} , we were able to obtain images for subject B with no readjustment of the IR sequence.

T_1^{B0} and T_2^{B0} Mapping. We acquired a coronal T_1^{B0} map of the head using a 2D spin echo imaging sequence (Fig. 2A) with 10 values of t_{T1}^{B0} distributed approximately logarithmically from 18 to 4,018 ms (Table 1, row 4). The acquisition time was 19 min, 20 s. The nominal resolution was 2.5×2.5 mm in-plane. The final image was computed pixelwise from a monoexponential fit of signal amplitude vs. t_{T1}^{B0} .

A major disadvantage of T_1^{B0} maps is the long acquisition time. However, it is well known that T_2 should approach T_1 at low magnetic fields (40) and the intrinsically high T_1 contrast at ULF is reflected in T_2 -weighted images, as demonstrated by Zotev et al. (29). The acquisition of a multiecho train, in which the signal decays with T_2 , thus permits T_1 -like contrast with a significant reduction of the image acquisition time. We therefore acquired T_2^{B0} -weighted images with a 2D CPMG sequence (Fig. 2A) using eight spin echoes with echo times distributed linearly between 74 and 1,257 ms (Table 1, row 5). A plot of signal amplitude vs. echo time was fitted pixelwise to a single exponential decay function to compute a T_2^{B0} image. The acquisition time was 4 min, 26 s. The nominal in-plane resolution was 2.5×1.9 mm.

Results

Fig. 3 shows examples of the 1D-localized signals used to determine T_1^{B0} . The scalp fat immediately under the dewar ($x = 0$) appears as a shoulder at $x = -6$ mm; the dip in the signal at $x = -9$ mm is due to the negligible skull signal. Some contaminating scalp fat signal, however, is expected in the region $-17 < x < -9$ mm because the skull is curved. The signal between -38 and -17 mm decays more slowly than that for $x < -38$ mm, and we interpret it as arising from CSF in the subarachnoid space and cortical sulci. The signal below the subarachnoid CSF ($-120 < x < -38$ mm) is dominated by faster relaxation, most likely from brain tissue with some contribution from CSF and blood.

T_1 (Scalp Fat). Scalp fat is spatially resolved in the region $-9 < x < 0$ mm (Fig. 3, gray region). An exponential fit of signal amplitude vs. t_{T1}^{B0} for this region found $T_1^{B0}(fat) = 96 \pm 2$ ms. The same procedure was carried out for the polarizing field data, yielding $T_1^{Bp}(fat) = 223 \pm 45$ ms.

T_1 (CSF). Scalp fat and brain tissue signals decay substantially by $t_{T1}^{B0} = 418$ ms, as illustrated in Fig. 3, suggesting that fitting the results for $t_{T1}^{B0} > 418$ ms permits their contributions to be neglected compared with the contribution of CSF. We expect blood T_1 to be intermediate between that of the relatively immobile brain tissue water and the free water of CSF. By fitting times above $t_{T1}^{B0} = 418$ ms and recognizing that the blood fraction is relatively small ($\sim 10\%$ of the total brain by volume), to a good approximation we are able to neglect the blood signal. An

Table 2. Values of T_1 used to calculate the IR sequence for Fig. 4

Tissue	T_1^{B0} (ms)	T_1^{Bp} (ms)
Scalp fat	96 ± 2	223 ± 45
CSF	$1,770 \pm 130$	$4,360 \pm 600$
Brain	85 ± 3	453 ± 117
Blood	190 ± 39	450^*

*This value was determined by a nulling experiment that did not yield an error bar.

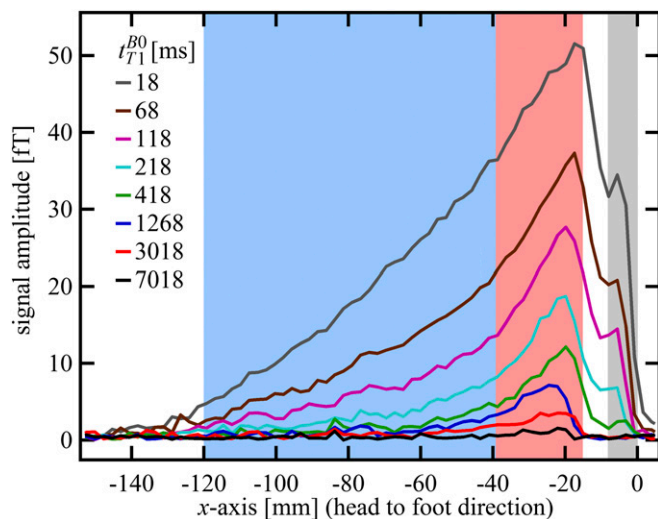


Fig. 3. One-dimensional images of the brain acquired with frequency encoding along the x axis; the nominal spatial resolution is 2.5 mm. Each 1D image was obtained at one of the eight values of $t_{T_1}^{B_0}$ listed on the figure. The bottom of the dewar and thus the top of the subject's head are at $x = 0$. The signal in the light gray region was integrated to perform exponential fits to obtain $T_1^{B_0}$ (fat). The same procedure was used for the light red and light blue regions to obtain $T_1^{B_0}$ (CSF) and $T_1^{B_0}$ (brain), respectively.

exponential fit to the integral of the signal in the region between -38 to -17 mm (Fig. 3, light red region) vs. $t_{T_1}^{B_0}$ for $t_{T_1}^{B_0} = 418$ – $7,018$ ms found $T_1^{B_0}(\text{CSF}) = 1,770 \pm 130$ ms. By comparison we found $T_1^{B_0}(\text{tap water}) \approx 2,200$ ms at room temperature.

Because the maximum duration of t_{Bp} is 720 ms, whereas we expect $T_1^{Bp}(\text{CSF})$ to be longer than $T_1^{B_0}(\text{CSF}) \sim 1,770$ ms, it is difficult to obtain an accurate estimate of $T_1^{Bp}(\text{CSF})$ using our system. Our attempts to use the signal from the region $-38 < x < -17$ mm and a range of t_{Bp} values with the maximum duration of 720 ms had

unacceptably large errors. We therefore adopted an in vivo value from the literature (47), $T_1^{Bp}(\text{CSF}) = 4,360 \pm 600$ ms, to set the IR sequence timing for 2D imaging.

T_1 (Brain Tissue). For brain tissue we integrated the signal beneath the region of the brain dominated by CSF, that is, $-120 < x < -38$ mm (Fig. 3, light blue region). A single exponential fit yielded an apparent relaxation time $T_1^{B_0}(\text{brain}) = 85 \pm 3$ ms. (We used this value to determine the IR timing of the 2D imaging sequence.) The acquired signal, however, contained unknown contributions from cerebral blood and CSF located deeper in the brain, as well as brain tissue. We consequently performed a triexponential fit to the signal amplitude vs. $t_{T_1}^{B_0}$ for $t_{T_1}^{B_0} = 18$ – $7,018$ ms, using our prior estimate of $T_1^{B_0}(\text{CSF}) = 1,770$ ms as a fixed value for one of the three T_1 coefficients. This yielded $T_1^{B_0}(\text{brain}) : 141 \pm 38$ ms and 61 ± 6 ms. These values compare reasonably well with literature values at 235 μT for GM and WM of 122 and 89 ms, respectively (48). Nevertheless, an alternative possibility is that the shorter $T_1^{B_0}$ represents brain tissue and the longer T_1 represents blood. The volume fraction implied for the 61-ms component of the triexponential fit was roughly three times that of the 141-ms species. We should exercise care, however, when interpreting the volume fractions returned from the fit because each component has an unknown weighting factor that depends on the T_1^{Bp} of each species. We return to the assignment issue in the context of 2D imaging, below.

Even though the region $-120 < x < -38$ mm contains a CSF component, we attempted a single exponential fit of the polarizing field data, leading to $T_1^{Bp}(\text{brain}) = 453 \pm 117$ ms. We next attempted biexponential and triexponential fits, first allowing all T_1 coefficients to fit freely and then testing fits with one T_1 held at 4360 ms (for CSF), but the results were inconclusive due to large fitting errors. This is unsurprising given that the maximum value of t_{Bp} , 720 ms, is less than or comparable to the likely T_1 values of the contributing sources. At 80 mT, we expect $T_1(\text{GM})$ and $T_1(\text{WM})$ to be around 900 and 500 ms, respectively (48).

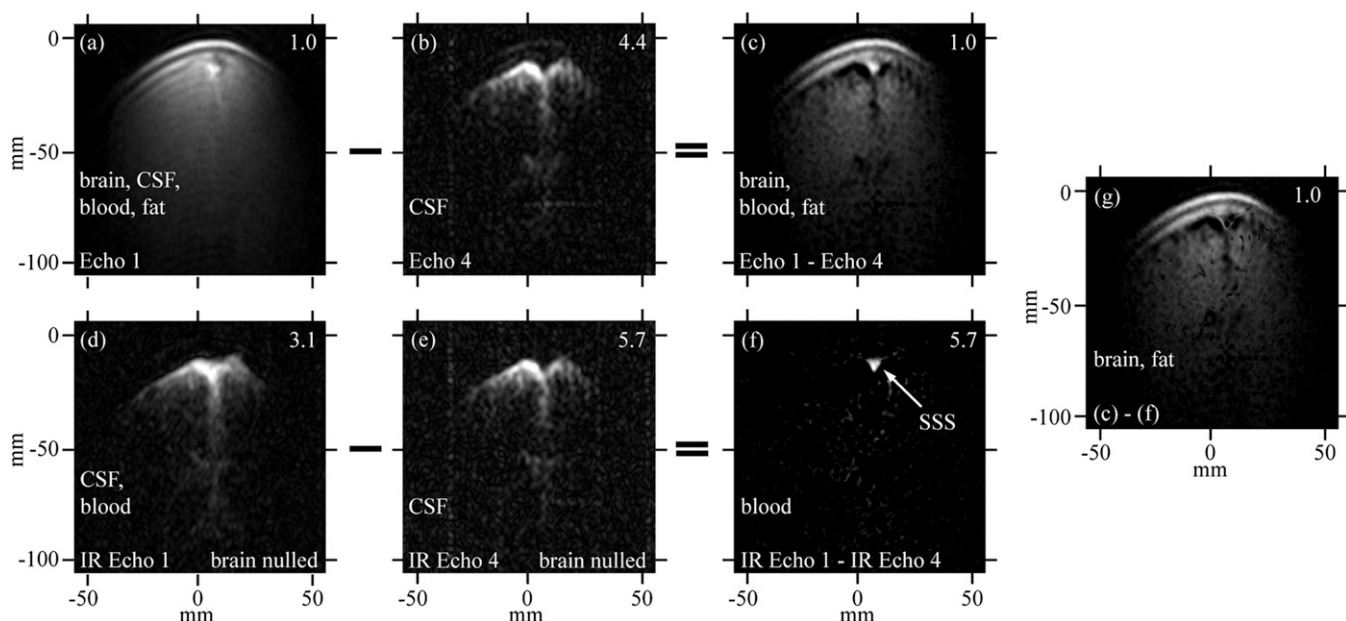


Fig. 4. 2D images of brain. Data acquired using an acquisition of a CPMG sequence (A and B) interleaved with an IR-CPMG sequence (D and E) with the inversion recovery delays adjusted to establish a signal null for brain tissue. C and F are obtained from the subtractions $A - B$ and $D - E$, respectively. G is the subtraction $C - F$. Image amplitudes have been scaled to enhance visualization of features: scaling factors are given in the top right corner of each image. The nominal in-plane resolution is 2.5 mm (z) \times 1.9 mm (x). The total imaging time was 25 min, 52 s. Frequency and phase encoding are along the z and x axes, respectively.

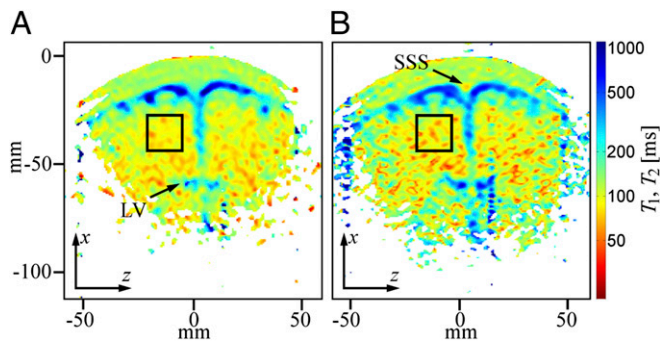


Fig. 5. 2D T_1 and T_2 maps of the brain. (A) T_1 map acquired in 19 min, 20 s. The nominal in-plane resolution is $2.5 \text{ mm} \times 2.5 \text{ mm}$. (B) T_2 map acquired in 4 min, 26 s. The nominal in-plane resolution is $2.5 \text{ mm} \times 1.9 \text{ mm}$. Black boxes indicate a region of interest used to derive an average relaxation time for brain tissue. The superior sagittal sinus location is indicated as SSS. Frequency and phase encoding are along the z and x axes, respectively.

T_1 (Blood). In principle, one might hope to measure blood localized in the SSS, which follows the curvature of the head along the midline. The SSS is a large caliber vessel and is located superficially, allowing for relatively efficient signal detection. In practice, however, the curvature of the SSS relative to the plane of the gradiometer loop resulted in the contamination of blood signals by signals from scalp fat, brain tissue, and CSF, and we were unable to estimate T_1 for blood using either 1D or 2D imaging of the head. In separate experiments (Figs. S1 and S2, and Table S1), we measured T_1 of blood in the cephalic vein of the forearm to be $T_1^{B0}(\text{blood}) = 190 \pm 39 \text{ ms}$ and $T_1^{Bp}(\text{blood}) \approx 450 \text{ ms}$. We note that $T_1^{B0}(\text{blood})$ is significantly longer than the value of 141 ms observed in the three-exponential fit to the brain tissue region of the 1D image, suggesting that the latter should indeed be assigned to GM.

Two-Dimensional Brain Imaging. The set of coronal head images shown in Fig. 4 was obtained in $\sim 26 \text{ min}$ using interleaved CPMG and IR-CPMG sequences. (Similar images for subject B are shown in Fig. S3.) The approximate thickness of these 2D images can readily be inferred from the fact that they are perpendicular to the plane of the lowest loop of the gradiometer. The maximum width of the images is $\sim 100 \text{ mm}$ —as expected, somewhat greater than the diameter of the loop (49). Because the field of view of the pickup loop is rotationally symmetric, the effective image thickness in the y direction is also about 100 mm. Fig. 4A was produced from the first echo of the CPMG sequence and shows scalp fat, brain tissue, blood, and CSF. The skull is the dark crescent between the scalp and brain, and blood in the SSS appears as a bright spot. Fig. 4B shows an image produced from the fourth echo of the CPMG acquisition, which was initiated at $3t_{E2} = 507 \text{ ms}$ after the first echo. The image is dominated by the CSF signal because of its long T_2 . Lateral ventricles and CSF-filled sulci are clearly visible. Blood and brain signals have decayed nearly to zero, but a faint trace of scalp fat remains because of its high SNR due to its proximity to the gradiometer. Fig. 4C shows the result of subtracting Fig. 4B from Fig. 4A pixel by pixel. Although the subtraction allows clear contrast of several components in the head, especially between brain tissue and the CSF-filled spaces (which are signal voids after subtraction), there is no evident contrast between WM and GM.

Fig. 4D and E show the first and fourth echoes of the IR-CPMG acquisition, respectively, with the IR sequence set to null signal from brain tissue. The similarity of both T_1^{B0} and T_1^{Bp} for scalp fat and brain tissue also reduces the fat signal considerably. In Fig. 4D, the image is predominantly CSF and blood. A further T_2 decay of $3t_{E2} = 507 \text{ ms}$ (the fourth echo) leaves only CSF (Fig.

4E). Subtracting Fig. 4E from Fig. 4D reveals a blood-only image (Fig. 4F), the most prominent feature of which is the SSS. Finally, subtracting Fig. 4F from Fig. 4C eliminates the blood to produce Fig. 4G, which shows only brain tissue and scalp fat.

The fact that the SSS stands out so vividly against the nulled brain in Fig. 4F supports our previous tentative assignment of $T_1^{B0} = 141 \text{ ms}$ to GM, rather than to blood. Thus, although we cannot differentiate GM and WM with the limited spatial resolution of our 2D images, our 1D imaging data confirm there is an intrinsic T_1^{B0} contrast (29, 49).

T_1^{B0} Map. Fig. 5A shows a coronal T_1^{B0} map of the head acquired using a 2D spin echo imaging sequence. The CSF and brain tissue are especially well contrasted. The T_1^{B0} (CSF) of 500–1,000 ms observed for CSF located in the subarachnoid space toward the top of the head is somewhat lower than the value $T_1^{B0}(\text{CSF}) = 1,770 \pm 130 \text{ ms}$ obtained from the 1D imaging data. The lower value in the 2D map probably arises from partial volume contamination from scalp fat and brain tissue and from our use of a monoexponential fit to data that included short t_{T1}^{B0} values. Despite having only 10 values of t_{T1}^{B0} , we attempted a biexponential fit to the same data and observed a longer T_1 component in the subarachnoid space that averaged around 1,500 ms, together with a shorter T_1 of around 120 ms, which is consistent with CSF contaminated by a significant partial volume effect from fat and/or brain tissue. However, the fit errors were sufficiently large that we did not attempt a detailed evaluation of the biexponential fit.

The T_1 observed in CSF-dominated regions deeper in the brain, such as the upper portion of the lateral ventricles (LVs), also exhibits pronounced partial volume effects arising from the faster relaxing brain tissue signals; the apparent T_1 is between 200 and 500 ms, intermediate between the T_1 values for brain tissue and CSF that we obtained from the 1D data. Partial volume effects are again expected due to the low through-plane spatial resolution. The SNR is also lower in the regions farther from the gradiometer, leading to higher fit errors.

To estimate T_1^{B0} in the brain tissue of Fig. 5A, we averaged voxels over an area of about 400 mm^2 (black box), avoiding regions with a large fraction of CSF, and found $T_1^{B0}(\text{brain}) = 88 \pm 1 \text{ ms}$. This value is in very good agreement with the $T_1^{B0}(\text{brain}) = 85 \pm 3 \text{ ms}$ obtained from the single exponential fit to the 1D images. Given the relatively low volume fraction of blood in the brain, it is perfectly reasonable that the value of 88 ms represents primarily a weighted average of GM and WM signals. The results of a biexponential fit to the same signal region, however, were inconclusive because of large fit errors.

T_2^{B0} Map. Fig. 5B shows a coronal T_2^{B0} map of the head using a 2D CPMG imaging sequence. The contrast in Fig. 5B is similar to that observed in the T_1^{B0} map of Fig. 5A, but there are subtle differences. In the subarachnoid space $T_2^{B0}(\text{CSF})$ is 400–800 ms, slightly shorter than the corresponding $T_1^{B0}(\text{CSF})$ values. The apparent $T_2^{B0}(\text{blood})$ of the SSS, 50–80 ms, is also short compared with $T_1^{B0}(\text{blood}) \approx 160 \text{ ms}$ in the same region of Fig. 5A. For both the CSF, which exhibits slow pulsatile flow, and the blood flowing in the SSS, we expect additional signal loss arising from the use of a constant frequency encoding gradient throughout the CPMG echo train, leading to apparent T_2^{B0} values that are lower than the true values and also lower than the corresponding T_1^{B0} values. A region of interest (black box) positioned within brain tissue, however, gives $T_2^{B0}(\text{brain}) = 88 \pm 2 \text{ ms}$, in remarkably good agreement with the value of T_1^{B0} from the same region in Fig. 5A. Evidently, the constant frequency encoding gradient produces negligible signal loss for the restricted motion of water in the brain tissue. A biexponential fit of signal amplitude vs. echo time was attempted for the brain region but yielded ambiguous results due to large fit errors.

In both Fig. 5 *A* and *B*, we observe contrast between tissue adjacent to the ventricles, the subarachnoid space and midline, compared with tissue farther from these CSF-dominated regions. It is tempting to assign the two tissues as GM and WM, respectively, but caution is warranted because of the partial volume effects of CSF that will be especially problematic for GM tissue located adjacent to the CSF-filled sulci. Because the apparent contrast between the brain tissue regions changes rapidly with small adjustments in the color amplitude scale, one should take care not to over interpret these images. Although we were able to identify two short T_1^{B0} values from the 1D imaging data and assigned them as GM and WM, we currently do not have the SNR or spatial resolution to separate these tissues in the 2D data unambiguously.

Discussion and Outlook

We have measured T_1 values at $B_0 \sim 130 \mu\text{T}$ for several constituents of the human head. Our quantitative results from 1D imaging agree reasonably well with previous estimates obtained at $46 \mu\text{T}$ (29) with one significant exception: we were able to separate the CSF signal from signals from other tissues, simply by waiting for the echoes from the blood and brain to decay, enabling us to obtain a more accurate estimate for $T_1(\text{CSF})$ of 1,770 ms. We believe, therefore, that the value of $T_1(\text{CSF}) = 344 \pm 9$ ms reported by Zotev et al. (29) was reduced below its true value by partial volume effects, particularly from brain tissue. An earlier study found $T_1 > 4$ s for in vivo CSF at $235 \mu\text{T}$ (47), suggesting that our observed value may still be reduced by the presence of brain tissue.

The ratio $T_1(\text{GM})/T_1(\text{WM})$ of 2.4 obtained in our work is significantly larger than the ratio of 1.2–1.5 observed at 1.5 and 3 T. This higher intrinsic brain tissue contrast is potentially less useful, however, because of the short absolute T_1 (and T_2) values. A further challenge is posed by CSF signals. The value of $T_1^{B0}(\text{CSF})$ is more than an order of magnitude greater than $T_1^{B0}(\text{brain})$, whereas at high field the ratio is typically a factor of 2–4. As a consequence, at ULF the proximity of cortical GM to CSF-filled spaces such as sulci implies that partial volume effects will be a concern for voxels having dimensions of millimeters. Thus, for practical applications it remains to be seen whether sufficient GM/WM tissue contrast can be established by virtue of T_1 (or T_2) weighting alone, or if a reduction of the CSF signal—for example, by nulling—will be required. If, as we propose below, the SNR could be increased by an order of magnitude it would become feasible to acquire small voxels containing a single species. This would enable ULFMRI to exploit fully the large intrinsic T_1 (or T_2) contrast and have sufficient contrast-to-noise (CNR) to separate WM and GM in 2D (and 3D) images.

Using CPMG and IR pulse sequences, modified to accommodate the requirements of ULFMRI, we presented 2D images showing various species in the brain that can be nulled or emphasized with a high degree of flexibility. For example, by subtracting an image acquired from the fourth echo of a CPMG sequence from that acquired from the first echo, we can remove the CSF component—which has a very long T_1 —to leave an image containing fat, brain tissue, and blood. By subtracting the same pair of spin echo images obtained following an IR to null out the brain tissue, we obtain an image solely of the cerebral blood. The combination of CPMG and IR sequences is a powerful technique to enhance the already substantial intrinsic T_1 and T_2 contrast at ULF.

We confirm the similarity between T_2 and T_1 contrast at ULF, as previously demonstrated by Zotev et al. (29, 49). A T_2 map of the brain resembles the corresponding T_1 map. Furthermore, compared with T_1 mapping, T_2 mapping offers the considerable advantage of a much shorter acquisition time.

The short T_1 (and T_2) values of brain tissues present a challenge for ULFMRI. Obtaining 3D voxels of 1–3 mm on a side, as

are obtained routinely in HF MRI, would require increasing the SNR in our system by an order of magnitude. In fact, such an improvement is not out of the question even with a single detector. First, one could increase the value of B_p over the volume of the head from its current 80 mT to, say, 150 mT, with a somewhat larger, water-cooled polarizing coil and a reasonably sized power supply. The higher value is within accepted international safety limits for the rate of change of magnetic field for a ramp down time of 10 ms. Second, our system magnetic field noise is limited by ambient noise to about $0.7 \text{ fHz}^{-1/2}$. A state-of-the-art SQUID with the same gradiometer, however, would have an intrinsic noise of about $0.1 \text{ fHz}^{-1/2}$. Although attaining such low noise in the presence of environmental magnetic field fluctuations may present a significant challenge, this combination of higher polarizing field and lower noise would yield the required order of magnitude increase in SNR. The use of an array of SQUIDs (25, 35) could potentially enhance the SNR of the detected signals considerably, improving both imaging speed and spatial resolution. We note that we polarize a much larger tissue volume—the entire head—than our single gradiometer coil can possibly image, so that implementing multiple sensors would not require additional polarizing coils. Further gains in SNR are achievable by reducing the time for the relays to disconnect the polarizing coil at the end of the polarizing pulse and by reducing the decay time of the eddy currents induced in the aluminum shield. Techniques involving actively driven cancellation coils (50–52), as well as engineering magnetic shielded rooms with multiple layers and shorter eddy current decay times, are being developed to reduce the amplitude of eddy currents, and it appears likely that the eddy current problem will be solved in the near future, thereby potentially improving the SNR. Finally, other techniques developed for HF MRI are applicable to ULFMRI. Parallel imaging with multiple sensors has already been demonstrated at ULF (27, 35). Imaging times may also be shortened by filling k -space asymmetrically using partial Fourier encoding (4, 53) in the phase encoding dimension.

Given sufficient SNR and resolution to permit anatomical imaging, there are many potential novel applications for ULFMRI involving the techniques we described for brain imaging. The combination of ULFMRI with MEG (35) would improve registration between the two modalities. This could be a significant advance because all magnetic source images require MRI for their interpretation. Another possible application for ULFMRI is cancer imaging. At ULF it has been demonstrated that T_1 for ex vivo healthy prostate tissue is about 40% longer than for ex vivo tumor tissue (34), suggesting that ULFMRI has the potential for in vivo imaging of prostate cancer, and possibly other cancers, without the need of a contrast agent.

Further intriguing applications are based on $T_{1\rho}$ contrast imaging, known as T_1 in the rotating frame. At HF, $T_{1\rho}$ contrast is produced by a long-duration spin locking B_1 field, typically 10–100 μT in amplitude, applied immediately after the application of an excitation pulse. During the spin locking period, the transverse magnetization decays in the effective field B_1 . Both ULF T_1 and HF $T_{1\rho}$ contrast mechanisms are strongly influenced by slow molecular dynamics, and it seems likely that the contrast generated by spin locking at HF could be obtained intrinsically at ULF without the high power deposition required by the use of long B_1 pulses.

There are a number of recent demonstrations of $T_{1\rho}$ contrast imaging that might be applicable at ULF. For example, the stimulated activation of gray matter has been shown to produce tissue-specific changes (54). In principle, the response to a neural stimulus could be measured in a combined MEG/ULFMRI system by recording the magnetic source signals and the T_1 changes in an interleaved fashion (15, 33). Recently, studies of ischemia following a stroke using $T_{1\rho}$ contrast (55) suggest that ULF T_1 imaging may provide a linear index of ischemia duration. Accurate determination of the time elapsed since a stroke can be

critically important to the choice of treatment options. Clinical applications of ULFMRI of brain might also include monitoring the progression of Alzheimer's and Parkinson diseases, based on changes in $T_{1\rho}$ contrast previously demonstrated at high field (56–58). Finally, high-field $T_{1\rho}$ contrast imaging has also been suggested as a potential biomarker for gene therapy of tumors (59, 60). Although ULFMRI still requires significant development to achieve clinically useful spatial resolution with an acceptable imaging time, it may ultimately find novel

clinical applications that complement those already established with HFMRI.

ACKNOWLEDGMENTS. We thank Steve Connolly for providing the water-cooled polarizing coil and Rick Redfern for constructing the subject chair. We are indebted to Sarah Busch, Michael Hatridge, Fredrik Oisjoen, and Koos Zevenhoven for constructing the shielded room with a short eddy-current decay time. This research was supported by the Donaldson Trust and National Institutes of Health Grant 5R21CA133338. K.B. gratefully acknowledges receipt of a fellowship from the Deutsche Forschungsgemeinschaft.

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